Spatial autocorrelation 2: Kriging

Michael Noonan



- 1. Review
- 2. Modelling Correlation Structures
- 3. Predicting from Spatial Autocorrelation Models
- 4. Considerations for Sampling Designs
- 5. Applied Kriging Analysis

Review

Review





Last lecture we started covering situations where the locations of points were an arbitrary artefact of the sampling process and not the variable of interest.

We also covered how autocorrelation contains a lot of information about these spatial processes, but that working with them requires a special set of tools.

We covered some of these tools (e.g., bubble plots, Moran's I), but identified semi-variograms as being particularly useful, objective, and as having a long, proven history.

$$\hat{\gamma}(h \pm \delta) := rac{1}{2|N(h \pm \delta)|} \sum_{(i,j) \in N(h \pm \delta)} |z_i - z_j|^2$$

I also told you that the shape of a dataset's empirical semi-variogram can provide clues on how to best model the autocorrelation in the data.

Today we will focus on how to fit models to semi-variograms, how to use these models to make predictions, and the implications for study design. DATA 589: Spatial Statistics

Modelling Correlation Structures



Semi-variogram have a number of key features that we should be looking for (sill? range? nugget? shape?).



Rainfall in Switzerland



Fulmaris glacialis densities



Source: gstat package



Soil copper concentrations



Source: gstat package



Okanagan Campus



Semi-variograms have a number of key features that we should be looking for (i.e., sill, range, nugget, shape).

So what?

Usefully, the different spatial correlation models all have differently shaped theoretical variograms.



Okanagan Campus













Separation Distance DATA 589: Spatial Statistics





Separation Distance
ar
$$\Phi = 1 - (1\frac{D}{\rho})I(d < \rho)$$



Fitting correlation models





The different correlation models are fit to the semi-variogram, usually (but not necessarily) via Ordinary Least Squares, and the best fit to the data is identified.



We're going to work with the dataset on forest composition in Tatarstan, Russia again.

The variable of interest is a measure of boreality (\sim percent boreal species at a site).



Linear spatial correlation in R



A linear spatial correlation structure can be applied via the fit.variogram() function with the argument vgm("Lin").





Other spatial correlations in R



Okanagan Campus



Other spatial correlations in R cont.



Okanagan Campus





We just fit 5 different autocorrelation models, but how do we know which is the best fit to the data?

#Ordered by lowest to highest SSErr
results <- results[order(results\$SSErr),]</pre>

 model
 SSErr

 1
 spherical
 0.06565859

 4
 exponential
 0.06942162

 2
 linear
 0.10490507

 3
 Gaussian
 0.14084834

 5
 nugget
 2.95142242





What does the selected model tell us about our data?

fit.spherical



Correlations persist for ${\sim}1.6$ km.

When $h \to \infty \gamma_s(h) = var(Z(\mathbf{s}))$ fit.spherical\$psill[2] + fit.spherical\$ psill[1] [1] 20.48798

var(data\$Bor) [1] 17.76566

Variance is slightly different (non-stationarity? small-sample-size-bias? model-misspecification?).



Residuals can be manually calculated.



How do these look? What should they look like?

BC THE UNIVERSITY OF BRITISH COLUMBIA Okanagan Campus

Density plot of residuals around the sill can be informative.

```
SILL <- residuals[which(fitted$gamma == max(fitted$gamma))]</pre>
```

```
plot(density(SILL))
```





We fit several spatial autocorrelation models:

Туре	Description	gstat Function
Nugget	0	vgm("Nug")
Linear	$\Phi = 1 - (1rac{D}{ ho})I(d < ho)$	vgm("Lin")
Spherical	$\Phi = 1(1-1.5(rac{d}{ ho})+0.5(rac{d}{ ho})3)I(d< ho)$	vgm("Sph")
Gaussian	$\Phi = 1 - e^{-\left(\frac{D}{\rho}\right)^{2'}}$	vgm("Gaus")
Exponential	$\Phi = 1 - e^{-rac{D}{ ho}}$	vgm("Exp")

The model structures can be difficult to interpret, but their variograms have very recognizable features. Familiarising yourself with them will help you quickly narrow down what structure to use.



...but there are a lot of different candidate models to choose from.

gstat::vgm()

	short	long
1	Nug	Nug (nugget)
2	Exp	Exp (exponential)
3	Sph	Sph (spherical)
4	Gau	Gau (gaussian)
5	Exc	Exclass (Exponential class/stable)
6	Mat	Mat (Matern)
7	Ste	Mat (Matern, M. Steins parameterization)
8	Cir	Cir (circular)
9	Lin	Lin (linear)
10	Bes	Bes (bessel)
11	Pen	Pen (pentaspherical)
12	Per	Per (periodic)
13	Wav	Wav (wave)
14	Hol	Hol (hole)
15	Log	Log (logarithmic)
16	Pow	Pow (power)
17	Spl	Spl (spline)
18	Leg	Leg (Legendre)
19	Err	Err (Measurement error)
20	Int	Int (Intercept)

Predicting from Spatial Autocorrelation Models



The form of the correlation model and parameter values are valuable in-and-of-themselves, but fitting these models is usually an intermediate step.

Typically, the goal of modelling these data is to predict to unsampled areas and map out the response variable.

There are many tools for interpolating spatial data, but we will focus on one of them: Kriging (based Danie Krige's MSc thesis).

There are also many forms of Kriging (ordinary, simple, universal, Bayesian, etc...), but we will focus (mostly) on ordinary Kriging.



In ordinary Kriging, $\hat{Z}(x_0)$ is assumed to be random variable located at an unobserved location x_0 , with a constant, unknown mean (Matheron, 1963).

 $\hat{Z}(x_0)$ is estimated from a linear combination of the observed values z_i and weights w_i :

$$\hat{Z}(x_0) = \begin{bmatrix} w_1 & w_2 & \cdots & w_N \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_N \end{bmatrix} = \sum_{i=1}^N w_i(x_0) Z(x_i)$$

The weights are critical, and intended to reflect the proximity of samples to the estimation location x_0 .



We're trying to predict $\hat{Z}(x_0)$ using the known values $Z(x_i)$, and their spatial dependences.



The fitted semi-variogram model describes the spatial dependence of the samples.

We can use this to calculate the covariance matrix (diagonal = σ^2 = sill, off-diagonals = $\hat{\gamma}(h)$)

and from that the weights (with $\sum_{i=1}^{N} w_i = 1$).



We're trying to predict $\hat{Z}(x_0)$ using $Z(x_i)$, and $\hat{\gamma}(h)$.





Usually we want to predict over a large spatial area.

```
# Grid over the sampled area
grid <- makegrid(data, n=200000)
names(grid) <- c("x", "y")</pre>
sp::coordinates(grid) <- c("x","y")</pre>
boreality.kriged <- krige(Bor ~ 1,
                           data,
                           newdata = grid,
                           model=fit.spherical)
head(boreality.kriged)
    coordinates var1.pred var1.var
1 (-2.89, 4.93) 12.21230 21.33647
 (6.71, 4.93) 12.20009 21.32484
2
3 (16.31, 4.93) 12.18724 21.31255
4 (25.91, 4.93)
                12.17376 21.29957
5 (35.51, 4.93)
                12.15965 21.28588
6 (45.11, 4.93) 12.14492 21.27143
```













We also get an estimate of the variance at x_0 . Do these patterns make sense?





Variance is lowest where we have data ($\sigma_{x_0}^2 = \text{nugget}$), and increases the further away from the samples we move.



Boreality

BC THE UNIVERSITY OF BRITISH COLUMBIA Okanagan Campus

Kriging is a spatial interpolation method, so what happens if we try to extrapolate?



How far out can we reasonably predict?



The Kriging weights (and therefore the predictions) are very sensitive to the fitted semi-variogram.



It's important to ensure the model is correctly specified.



The Kriging weights (and therefore the predictions) are very sensitive to the fitted semi-variogram.



Boreality - Gaussian Model

It's important to ensure the model is correctly specified.



The Kriging weights (and therefore the predictions) are very sensitive to the fitted semi-variogram.



It's important to ensure the model is correctly specified.



Est. the weights requires a matrix inversion (doesn't scale well).

```
# predict at 100 locations
grid100 <- makegrid(data, n=100)
sp::coordinates(grid1) <- c("x1","x2")</pre>
```

```
system.time(
    krige(Bor ~ 1,
        data,
        newdata = grid100,
        model=fit.spherical))
```

```
[using ordinary kriging]
user system elapsed
0.049 0.001 0.050
```

predict at 10000 locations grid10000 <- makegrid(data, n=10000) sp::coordinates(grid10000) <- c("x1","x2")</pre>

```
system.time(
    krige(Bor ~ 1,
        data,
        newdata = grid10000,
        model=fit.spherical))
```

200

```
[using ordinary kriging]
user system elapsed
2.066 0.024 2.096
```

4,000 times longer!



Considerations for Sampling Designs



Experimental designs that do not consider spatial autocorrelation risk being over/under-sampled.

Corrections exist to deal with issues of statistical bias, but they can't inject more information into a dataset when none exists.



Good study design should consider spatial autocorrelation a priori.

If you had to collect more data for the boreality study how far apart would you sample? $\lesssim 1600m$ to see the autocorrelation, $\gtrsim 1600m$ for IID data or for the mean/sill.

Applied Kriging Analysis



Coleby & Grist (2019) used a semi-variograms and kriging to map the distribution of marine plastic pollution in Hong Kong.





Fitting semi-variograms to spatial data can leverage the information contained in the autocorrelation structure and tell us a lot about the processes.

Kriging is a valuable tool for interpolating from spatially referenced data, but is not without limitations.

Kriging leverages information contained in the autocorrelation structure, but what about information contained in covariates?

Next lecture we will cover Kriging with covariates.

References

- Ballabio, C., Borrelli, P., Spinoni, J., Meusburger, K., Michaelides, S., Beguería, S., Klik, A., Petan, S., Janeček, M., Olsen, P., Aalto, J., Lakatos, M., Rymszewicz, A., Dumitrescu, A., Tadić, M.P., Diodato, N., Kostalova, J., Rousseva, S., Banasik, K., Alewell, C. & Panagos, P. (2017). Mapping monthly rainfall erosivity in europe. *Science of The Total Environment*, 579, 1298–1315.
- Bell, T., Campbell, S., Liverman, D.G., Allison, D. & Sylvester, P. (2010). Environmental and potential human health legacies of non-industrial sources of lead in a canadian urban landscape – the case study of st john's, newfoundland. *International Geology Review*, 52, 771–800.
- Coleby, A.M. & Grist, E.P. (2019). Prioritized area mapping for multiple stakeholders through geospatial modelling: A focus on marine plastics pollution in hong kong. Ocean & Coastal Management, 171, 131–141.
- Feeney, C., Cosby, B., Robinson, D., Thomas, A., Emmett, B. & Henrys, P. (2022). Multiple soil map comparison highlights challenges for predicting topsoil organic carbon concentration at national scale. *Scientific reports*, 12, 1–13.
- Matheron, G. (1963). Principles of geostatistics. Economic geology, 58, 1246-1266.